Formal Analysis of Population Protocols

Michael Blondin

Joint work with Javier Esparza, Stefan Jaax,

Antonín Kučera and Philipp J. Meyer



Population protocols: distributed computing model for massive networks of passively mobile finite-state agents

Overview



Can model *e.g.* networks of passively mobile sensors and chemical reaction networks

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Protocols compute predicates of the form $\varphi \colon \mathbb{N}^d \to \{0, 1\}$ e.g. if φ is unary, then $\varphi(n)$ is computed by n agents

Overview



Population protocols: distributed computing model for massive networks of passively mobile finite-state agents

This talk: overview of recent advances on the formal analysis of population protocols

- anonymous mobile agents with very few resources
- agents change states via random pairwise interactions
- each agent has opinion true/false
- computes by stabilizing agents to some opinion

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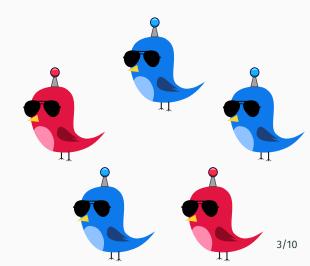


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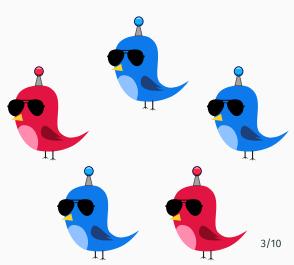


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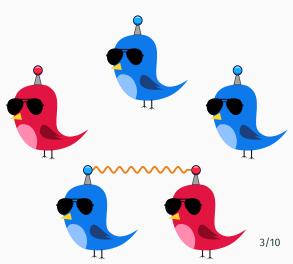




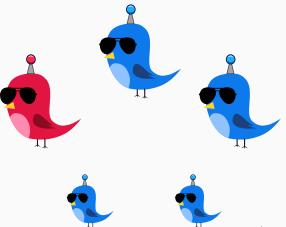
- Two large birds of different colors become small and blue
- Large birds convert small birds to their color



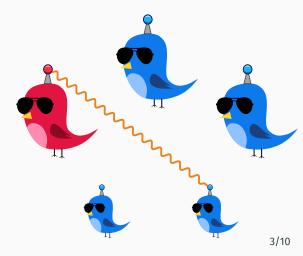
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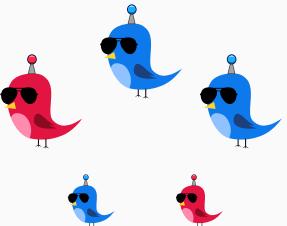
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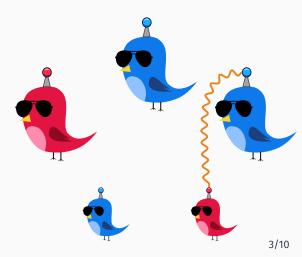
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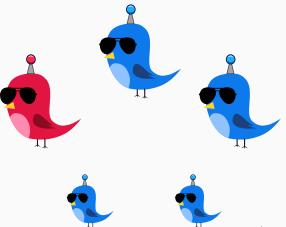
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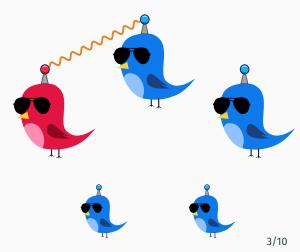
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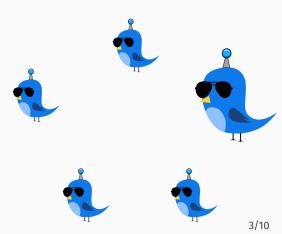
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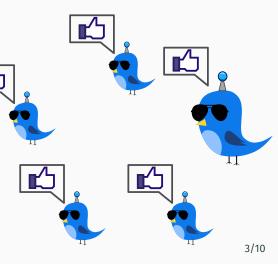
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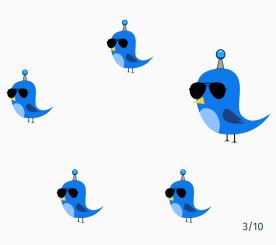
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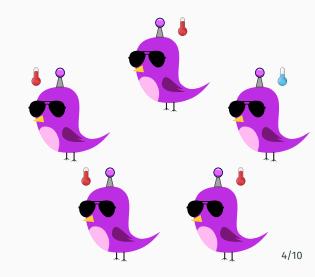
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- **To break ties:** small blue birds convert small red birds

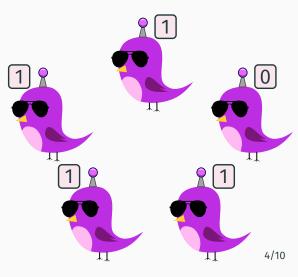


Are there at least 4 sick birds?



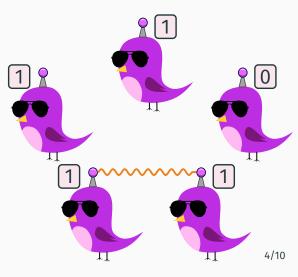
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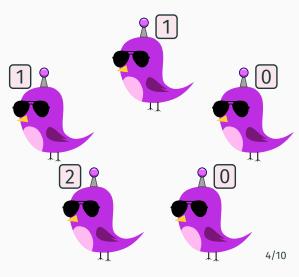
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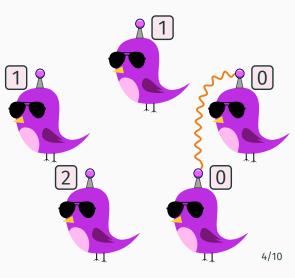
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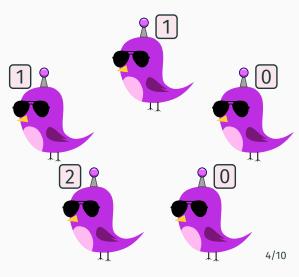
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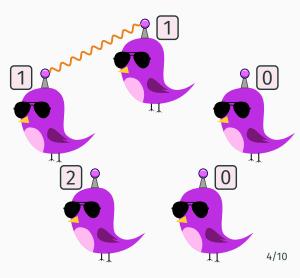
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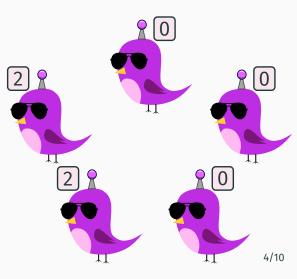
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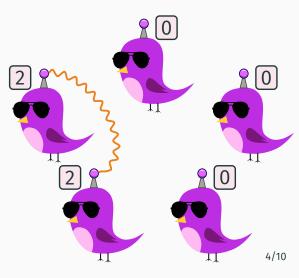
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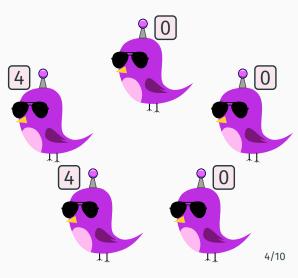
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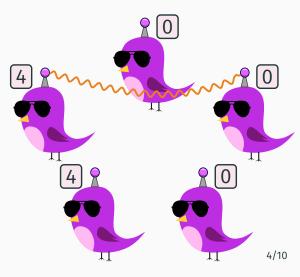
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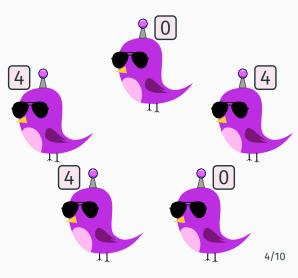
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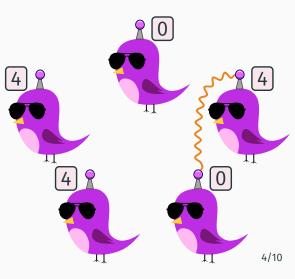
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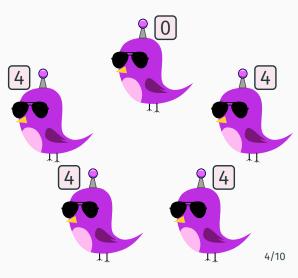
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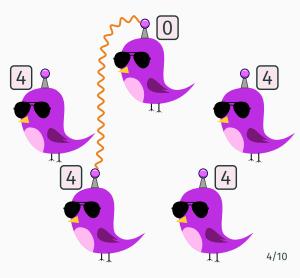
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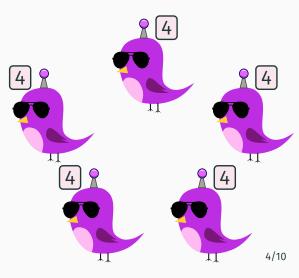
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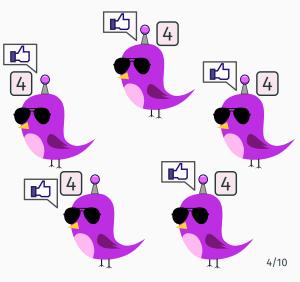
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Demonstration

- States: finite set Q
- Opinions: $O: Q \rightarrow \{0, 1\}$

 $I \subset Q$

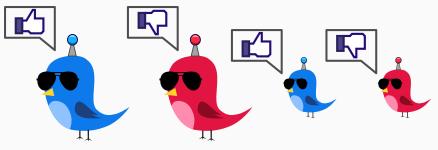
- Initial states:
- Transitions: $T \subseteq Q^2 \times Q^2$



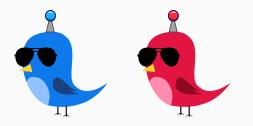
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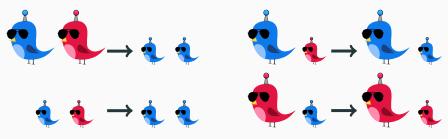
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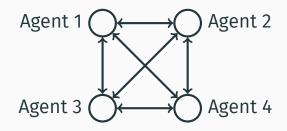
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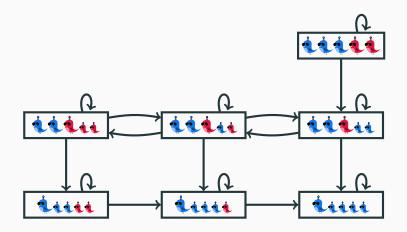
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Interaction graph:

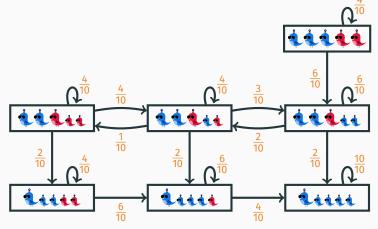


Reachability graph:

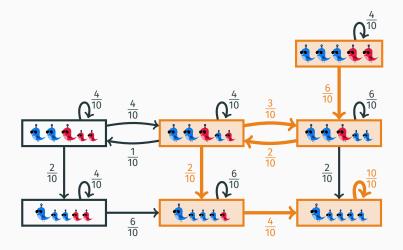


Underlying Markov chain:

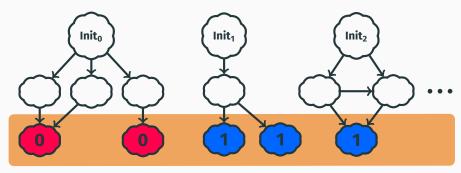
(pairs of agents are picked uniformly at random)



A run is an infinite path:



A protocol computes a predicate $\varphi \colon \mathbb{N}' \to \{0, 1\}$ if runs reach common stable consensus with probability 1



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Expressive power

Angluin, Aspnes, Eisenstat PODC'06

Population protocols compute precisely predicates definable in Presburger arithmetic, *i.e.* $FO(\mathbb{N}, +, <)$

Other variants considered:

- Approximate protocols
- Protocols with leaders
- Protocols with failures
- Trustful protocols
- Mediated protocols, etc.

e.g. Angluin, Aspnes, Eisenstat DISC'07 Angluin, Aspnes, Eisenstat Dist. Comput.'08 Delporte-Gallet *et al.* DCOSS'06 Bournez, Lefevre, Rabie DISC'13 Michail, Chatzigiannakis, Spirakis TCS'11

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Formal analysis of protocols

Protocols can become complex, even for $B \ge R$:

Fast and Exact Majority in Population Protocols

Dan Alistarh Rati Gelashvili^{*} Microsoft Research MIT

Milan Vojnović Microsoft Research

 $\begin{array}{ll} 1 & weight(x) = \left\{ \begin{array}{ll} |x| & \text{if } x \in StrongStates \text{ or } x \in WeakStates; \\ 1 & \text{if } x \in IntermediateStates. \end{array} \right. \\ \begin{array}{ll} 2 & sgn(x) = \left\{ \begin{array}{ll} 1 & \text{if } x \in \{+0, 1_d, \dots, 11, 3, 5, \dots, m\}; \\ -1 & \text{otherwise.} \end{array} \right. \end{array}$ 3 $value(x) = san(x) \cdot weight(x)$ /* Functions for rounding state interactions */ 4 $\phi(x) = -1_1$ if $x = -1; 1_1$ if x = 1; x, otherwise 5 $R_1(k) = \phi(k \text{ if } k \text{ odd integer}, k-1 \text{ if } k \text{ even})$ 6 R_↑(k) = φ(k if k odd integer, k+1 if k even) $\begin{array}{l} \textbf{7} \hspace{0.5cm} Shift-to-Zero(x) = \left\{ \begin{array}{ll} -1_{j+1} & \text{if } x = -1_{j} \text{ for some index } j < d \\ 1_{j+1} & \text{if } x = -1_{j} \text{ for some index } j < d \\ x & \text{otherwise} \end{array} \right. \\ \textbf{8} \hspace{0.5cm} Sign-to-Zero(x) = \left\{ \begin{array}{ll} -0 & \text{if } sgn(x) > 0 \\ 0 & \text{otherwise.} \end{array} \right. \end{array}$ 9 procedure update $\langle x, y \rangle$ if (weight(x) > 0 and weight(y) > 1) or (weight(y) > 0 and weight(x) > 1) then 10 $x' \leftarrow R_{\downarrow}\left(\frac{value(x)+value(y)}{2}\right)$ and $y' \leftarrow R_{\uparrow}\left(\frac{value(x)+value(y)}{2}\right)$ 11 12 else if $weight(x) \cdot weight(y) = 0$ and value(x) + value(y) > 0 then 13 if $weight(x) \neq 0$ then $x' \leftarrow Shift-to-Zero(x)$ and $y' \leftarrow Sign-to-Zero(x)$ 14 else $y' \leftarrow Shift-to-Zero(y)$ and $x' \leftarrow Sign-to-Zero(y)$ else if $(x \in \{-1_d, +1_d\}$ and weight(y) = 1 and $sgn(x) \neq sgn(y)$) or 15 16 $(y \in \{-1_d, +1_d\}$ and weight(x) = 1 and $sgn(y) \neq sgn(x)$ then $x' \leftarrow -0$ and $y' \leftarrow +0$ 17 18 else 19 $x' \leftarrow Shift-to-Zero(x)$ and $y' \leftarrow Shift-to-Zero(y)$

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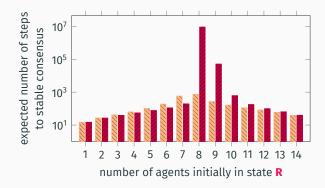
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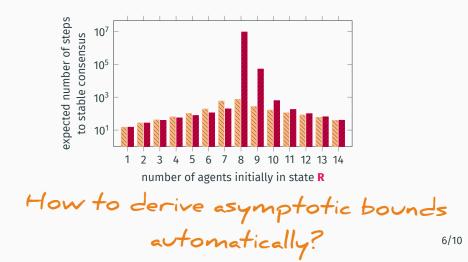
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Convergence speed may vary wildly, challenging to establish bounds



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Number of states corresponds to amount of memory, relevant to keep it minimal for embedded systems

- B ≥ R requires at least 4 states (Mertzios et al. ICALP'14)
- X ≥ C requires at most c + 1 states

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- **B 2 R** requires at least 4 states (Mertzios *et al.* ICALP'14)
- X ≥ C requires at most c + 1 states

What is the state complexity of common predicates?

Formal analysis of protocols

1. Automatic verification of correctness

- Decidability Esparza, Ganty, Leroux, Majumdar CONCUR'15, FSTTCS'16
- Towards efficient verification B., Esparza, Jaax, Meyer PODC'17
- Complete tool B., Esparza, Jaax CAV'18

2. Automatic analysis of convergence speed

• First procedure B., Esparza, Kučera (submitted to CONCUR'18)

3. State complexity of protocols w.r.t. predicates

• Study of linear inequalities

B., Esparza, Jaax STACS'18

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- PAT: model checker with global fairness (Sun, Liu, Song Dong and Pang CAV'09)
- bp-ver: graph exploration

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Only for populations of fixed size!

Sometimes possible to verify all sizes:

• Verification with the interactive theorem prover Coq (Deng and Monin TASE'09)

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Not automatic!

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Challenge: verifying automatically <u>all</u> sizes

Testing whether a protocol computes φ amounts to testing:

 $\neg \exists C, D: C \xrightarrow{*} D \land$ C is initial \land D is bottom \land opinion(D) $\neq \varphi(C)$ **PODC'17**

Testing whether a protocol computes φ amounts to testing:

$\neg \exists C, D: C \xrightarrow{*} D \land$ C is initial \land D is bottom \land opinion(D) $\neq \varphi(C)$

As difficult as verification

PODC'17

 $\neg \exists C, D: C \xrightarrow{*} D \land$ C is initial \land D is bottom \land opinion(D) $\neq \varphi(C)$

Relaxed with Presburger-definable overapproximation

$\neg \exists C, D: C \xrightarrow{*} D \land$ C is initial \land D is bottom \land opinion(D) $\neq \varphi(C)$

Difficult to express

$\neg \exists C, D: C \xrightarrow{*} D \land$ C is initial \land D is terminal \land opinion(D) $\neq \varphi(C)$

Most protocols are terminating!

$\neg \exists C, D: C \xrightarrow{*} D \land$ C is initial \land D is terminal \land opinion(D) $\neq \varphi(C)$

Testable with an SMT solver

$\neg \exists C, D: C \xrightarrow{*} D \land$ C is initial \land D is terminal \land opinion(D) $\neq \varphi(C)$

Protocol termination tested by structural analysis + SMT solving 7/10 Random variable *Steps*:

assigns to each run σ the smallest k s.t. σ_k in stable consensus

Maximal expected termination time

We are interested in $\mathit{time} \colon \mathbb{N} \to \mathbb{N}$ where

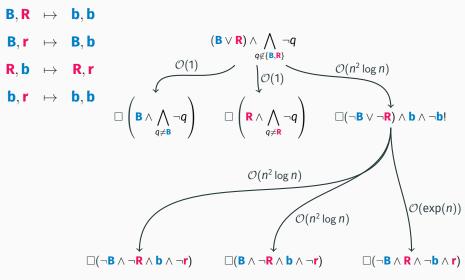
 $time(n) = \max\{\mathbb{E}_C[Steps] : C \text{ is initial and } |C| = n\}$

Our approach:

- Most protocols are naturally designed in stages
- Construct these stages automatically
- Derive upper bounds on time(n)

from stages structure

Analysis of termination time



8/10

- Can report: $\mathcal{O}(1), \mathcal{O}(n^2), \mathcal{O}(n^2 \log n), \mathcal{O}(n^3), \mathcal{O}(\text{poly}(n)) \text{ or } \mathcal{O}(\exp(n))$
- Tested on various protocols from the literature

Peregrine: **>= Haskell** + Microsoft Z3 + JavaScript

peregrine.model.in.tum.de

- Design of protocols
- Manual and automatic simulation
- Statistics of properties such as termination time
- Automatic verification of correctness
- More to come!

CAV'18

Demonstration

Population protocols can be formally analyzed automatically:

- Verification of correctness
- Analysis of expected termination time
- Tool support!

Ongoing investigation of state complexity

ERC Advanced Grant -

PaVeS: Parameterized Verification and Synthesis

- Goal: Develop proof and synthesis techniques for distributed algorithms working correctly for an arbitrary number of processes
- PI: Javier Esparza (esparza@in.tum.de), TU Munich
- Start of the project: Sept. 1, 2018
- Start of the PhDs/Postdocs: flexible, from Sept. 1, 2018 to about Sept. 1, 2019

Thank you! Vielen Dank!